Getting to the CORE of Complex Event Recognition

Stijn Vansummeren UHasselt, Data Science Institute

- 1. Present a logic for CER.
- 2. Introduce CEA, an automaton model for CER.
- 3. Explain our algorithm for processing CEA in constant-time per event.
- 4. Discuss limitations and open questions.

- 1. Present a logic for CER.
- 2. Introduce CEA, an automaton model for CER.
- 3. Explain our algorithm for processing CEA in constant-time per event.
- 4. Discuss limitations and open questions.



A Formal Framework for Complex Event Recognition ACM TODS 46(4), 2021

| Harris Backs Fill Chin subscription d | Michael Annual States | Robris Doubing PECChevanitol@b Cale Parmentation1 |
|---|-------------------------|---|
| | at services the service | an total and the |
| | | |

CORE: a Complex Event Recognition Engine VLDB 2022

- 1. Present a logic for CER.
- 2. Introduce CEA, an automaton model for CER.
- 3. Explain our algorithm for processing CEA in constant-time per event.
- Discuss limitations and open questions. 4.





Marco Bucchi

Alejandro Grez



Andrés Quintana PUC Chile, IMFD



Cristian Riveros



Martin Ugarte



Outline

A logic for CER

An automaton model for CER

Evaluation algorithm

The CORE complex event recognition engine

Open questions

"[...] CEP languages are often oversimplified, providing only a small set of operators, insufficient to express a number of desirable patterns and the rules to combine incoming information to produce new knowledge. Even worse, the semantics of such languages is usually given only informally, which leads to ambiguities and makes it difficult compare the different proposals."

G. Cugola and A. Margara

"TESLA: A formally defined event specification language", DEBS 2010.

"[...] CEP languages are often oversimplified, providing only a small set of operators, insufficient to express a number of desirable patterns and the rules to combine incoming information to produce new knowledge. Even worse, the semantics of such languages is usually given only informally, which leads to ambiguities and makes it difficult compare the different proposals."

G. Cugola and A. Margara

"TESLA: A formally defined event specification language", DEBS 2010.

See also [1] and [2].

[1] D. Zimmer and R. Unland

"On the semantics of complex events in active database management systems." ICDE 1999.

[2] N. Giatrakos, E. Alevizos, A. Artikis, A. Deligiannakis, M. N. Garofalakis

"Complex event recognition in the Big Data era: a survey." VLDB J. 29(1), 2020.

What do we expect for a query language for CER?

What do we expect for a query language for CER?

1. Formal syntax and semantics.

"For every query and stream, the output will be defined precisely."

2. Declarative, denotational semantics.

"The semantics will specify what the output is, but not how to compute it."

3. Composable language.

"The language operators can be combined as free as possible."

What do we expect for a query language for CER?

1. Formal syntax and semantics.

"For every query and stream, the output will be defined precisely."

2. Declarative, denotational semantics.

"The semantics will specify what the output is, but not how to compute it."

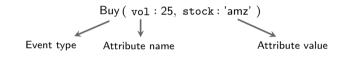
3. Composable language.

"The language operators can be combined as free as possible."

Complex Event Logic (CEL) is our proposal for a CER query language with these properties.

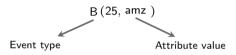
"A stream is a sequence of events where each event is represented as a tuple."

Event:



"A stream is a sequence of events where each event is represented as a tuple."

Event:



"A stream is a sequence of events where each event is represented as a tuple."

"A stream is a sequence of events where each event is represented as a tuple."

"A stream is a sequence of events where each event is represented as a tuple."

$$\begin{array}{c} \hline \mathsf{B}(16,a) \\ \hline \mathsf{B}(23,c) \\ \uparrow \\ 1 \\ \end{array} \begin{array}{c} \mathsf{S}(16,b) \\ \hline \mathsf{B}(25,a) \\ \end{array} \begin{array}{c} \mathsf{S}(11,c) \\ \mathsf{S}(12,d) \\ \end{array} \end{array} \cdots$$

"A stream is a sequence of events where each event is represented as a tuple."

$$\begin{array}{c} (B(16,a)) \\ (B(23,c)) \\ (S(16,b)) \\ (B(25,a)) \\ (S(11,c)) \\ (S(12,d)) \\$$

"A stream is a sequence of events where each event is represented as a tuple."

$$\begin{array}{c} (B(16,a)) \\ (B(23,c)) \\ (S(16,b)) \\ (B(25,a)) \\ (S(11,c)) \\ (S(12,d)) \\$$

"A stream is a sequence of events where each event is represented as a tuple."

$$\begin{array}{c} \hline \mathsf{B}(16,a) \\ \hline \mathsf{B}(23,c) \\ \hline \mathsf{S}(16,b) \\ \hline \mathsf{B}(25,a) \\ \hline \mathsf{S}(11,c) \\ \hline \mathsf{S}(12,d) \\ \hline \mathsf{4} \\ \end{array} \\ \begin{array}{c} \cdots \\ \mathsf{4} \\ \end{array}$$

"A stream is a sequence of events where each event is represented as a tuple."

"A stream is a sequence of events where each event is represented as a tuple."

"A stream is a sequence of events where each event is represented as a tuple."

$$(B_0(16, a) (B_1(23, c) (S_2(16, b) (B_3(25, a) (S_4(11, c) (S_5(12, d)) \cdots))))$$

"A stream is a sequence of events where each event is represented as a tuple."

Definition

A complex event is a pair ([i,j], C) where

• [i,j] is an interval that denotes the start and end of the complex event;

 S_2

B₃

S₄

S₅

 S_6

B₇

 B_8

B₉

. . .

• $C \subseteq \{i, i+1, \ldots, j\}$ is a finite set of selected events.

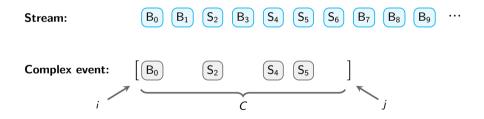
 B_1

 B_0

Definition

A complex event is a pair ([i,j], C) where

- [i,j] is an interval that denotes the start and end of the complex event;
- $C \subseteq \{i, i+1, \ldots, j\}$ is a finite set of selected events.



Definition

A complex event is a pair ([i,j], C) where

- [i,j] is an interval that denotes the start and end of the complex event;
- $C \subseteq \{i, i+1, \ldots, j\}$ is a finite set of selected events.



Definition

- A complex event is a pair ([i,j], C) where
 - [i,j] is an interval that denotes the start and end of the complex event;
 - $C \subseteq \{i, i+1, \ldots, j\}$ is a finite set of selected events.



"Complex Event Recognition (CER) is the act of recognizing complex events in a stream of primitive events."

Input:

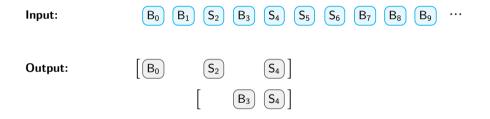


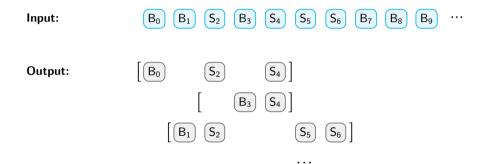
"Complex Event Recognition (CER) is the act of recognizing complex events in a stream of primitive events."



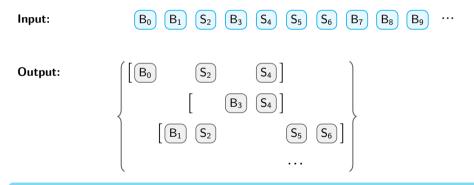
Output:







"Complex Event Recognition (CER) is the act of recognizing complex events in a stream of primitive events."



CER queries recognize complex events and extract them

Complex event logic (CEL)

CEL syntax $\varphi := R$

R is an event type.

 $\begin{array}{rcl} \mathsf{CEL \ syntax} \\ \varphi & \coloneqq & R & \mid \varphi; \varphi & \mid \varphi \, \mathsf{OR} \, \varphi & \mid \varphi + \end{array}$

R is an event type.

CEL syntax

 $\varphi := R \mid \varphi; \varphi \mid \varphi \text{ OR } \varphi \mid \varphi + \mid \varphi \text{ AS } X$

- R is an event type.
- X is a variable.

CEL syntax

 $\varphi := R | \varphi; \varphi | \varphi \text{ OR } \varphi | \varphi + | \varphi \text{ AS } X | \varphi \text{ FILTER } P(\overline{X})$

- R is an event type.
- X is a variable.
- $P(\overline{X})$ is a predicate over variables $\overline{X} = X_1, \ldots, X_k$.

CEL syntax

 $\varphi := R \mid \varphi; \varphi \mid \varphi \text{ OR } \varphi \mid \varphi + \mid \varphi \text{ AS } X \mid \varphi \text{ FILTER } P(\overline{X}) \mid \pi_{\overline{X}}(\varphi)$

- R is an event type.
- X is a variable.
- $P(\overline{X})$ is a predicate over variables $\overline{X} = X_1, \ldots, X_k$.

CEL syntax

 $\varphi := R \mid \varphi; \varphi \mid \varphi \text{ or } \varphi \mid \varphi + \mid \varphi \text{ as } X \mid \varphi \text{ filter } P(\overline{X}) \mid \pi_{\overline{X}}(\varphi)$

- R is an event type.
- X is a variable.
- $P(\overline{X})$ is a predicate over variables $\overline{X} = X_1, \ldots, X_k$.

Example of a CEL formula

 $\varphi = (B; (S + AS X); B)$ FILTER SameStock(X)

CEL syntax

 $\varphi := R \mid \varphi; \varphi \mid \varphi \text{ OR } \varphi \mid \varphi + \mid \varphi \text{ AS } X \mid \varphi \text{ Filter } P(\overline{X}) \mid \pi_{\overline{X}}(\varphi)$

- R is an event type.
- X is a variable.
- $P(\overline{X})$ is a predicate over variables $\overline{X} = X_1, \ldots, X_k$.

Example of a CEL formula

 $\varphi = (B; (S + AS X); B)$ FILTER SameStock(X)

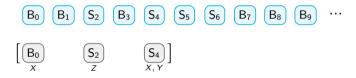
Variables in CEL represent sets of events (i.e. complex events)

Definition

Given a set of variables \mathcal{X} , a valuation V is a pair $([i,j],\mu)$ with $\mu: \mathcal{X} \to 2^{\mathbb{N}}$ a function that maps each variable $X \in \mathcal{X}$ to a finite set $\mu(X) \subseteq \{i, \ldots, j\}$.

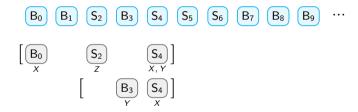
Definition

Given a set of variables \mathcal{X} , a valuation V is a pair $([i,j],\mu)$ with $\mu: \mathcal{X} \to 2^{\mathbb{N}}$ a function that maps each variable $X \in \mathcal{X}$ to a finite set $\mu(X) \subseteq \{i, \ldots, j\}$.



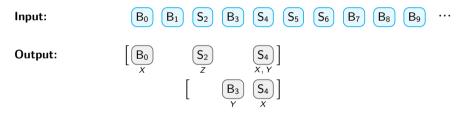
Definition

Given a set of variables \mathcal{X} , a valuation V is a pair $([i,j],\mu)$ with $\mu: \mathcal{X} \to 2^{\mathbb{N}}$ a function that maps each variable $X \in \mathcal{X}$ to a finite set $\mu(X) \subseteq \{i, \ldots, j\}$.



Definition

Given a set of variables \mathcal{X} , a valuation V is a pair $([i,j],\mu)$ with $\mu: \mathcal{X} \to 2^{\mathbb{N}}$ a function that maps each variable $X \in \mathcal{X}$ to a finite set $\mu(X) \subseteq \{i, \ldots, j\}$.

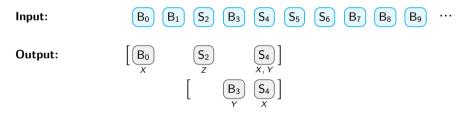


CEL auxiliary semantics (informally)

The valuation semantics of CEL formula φ is a function $\llbracket \varphi \rrbracket$ that maps a stream S to a set of valuations.

Definition

Given a set of variables \mathcal{X} , a valuation V is a pair $([i,j],\mu)$ with $\mu: \mathcal{X} \to 2^{\mathbb{N}}$ a function that maps each variable $X \in \mathcal{X}$ to a finite set $\mu(X) \subseteq \{i, \ldots, j\}$.

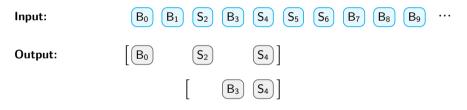


CEL semantics

The complex event semantics $\llbracket \varphi \rrbracket$ of CEL formula φ is obtained from $\llbracket \varphi \rrbracket$ by returning all events in the image of μ .

Definition

Given a set of variables \mathcal{X} , a valuation V is a pair $([i,j],\mu)$ with $\mu: \mathcal{X} \to 2^{\mathbb{N}}$ a function that maps each variable $X \in \mathcal{X}$ to a finite set $\mu(X) \subseteq \{i, \ldots, j\}$.



CEL semantics

The complex event semantics $\llbracket \varphi \rrbracket$ of CEL formula φ is obtained from $\llbracket \varphi \rrbracket$ by returning all events in the image of μ .

$$\begin{array}{cccc} R & \varphi; \varphi & \varphi & \text{OR } \varphi & \varphi^+ & \varphi & \text{AS } X & \varphi & \text{FILTER } P(\overline{X}) & \pi_{\overline{X}}(\varphi) \\ \\ & & & & \\ \llbracket R \rfloor (\mathcal{S}) & = & \{ V \mid V(\text{time}) = [i,i] \land \text{type}(\mathcal{S}[i]) = R \\ & & \land & V(R) = \{i\} \land \forall X \neq R. \ V(X) = \emptyset \end{array}$$



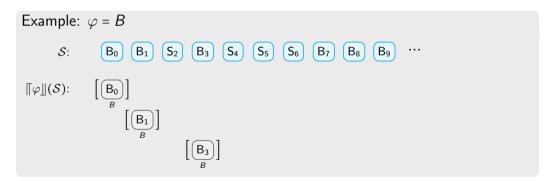
$$R \qquad \varphi; \varphi \qquad \varphi \ \mathsf{OR} \ \varphi \qquad \varphi + \varphi \ \mathsf{AS} \ X \qquad \varphi \ \mathsf{FILTER} \ P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$[[R]](S) = \{V \mid V(\mathsf{time}) = [i, i] \land \ \mathsf{type}(S[i]) = R$$
$$\land \ V(R) = \{i\} \land \ \forall X \neq R. \ V(X) = \emptyset \}$$



$$R \qquad \varphi; \varphi \qquad \varphi \ \mathsf{OR} \ \varphi \qquad \varphi + \varphi \ \mathsf{AS} \ X \qquad \varphi \ \mathsf{FILTER} \ P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$[[R]](S) = \{V \mid V(\mathsf{time}) = [i, i] \land \ \mathsf{type}(\mathcal{S}[i]) = R \land V(R) = \{i\} \land \ \forall X \neq R. \ V(X) = \emptyset \}$$



$$R \qquad \varphi; \varphi \qquad \varphi \ \mathsf{OR} \ \varphi \qquad \varphi^+ \qquad \varphi \ \mathsf{AS} \ X \qquad \varphi \ \mathsf{FILTER} \ P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$[[R]](S) = \{ V \mid V(\mathsf{time}) = [i, i] \land \ \mathsf{type}(\mathcal{S}[i]) = R \\ \land \ V(R) = \{i\} \land \ \forall X \neq R. \ V(X) = \emptyset \}$$



$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \quad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$\llbracket \varphi_1; \varphi_2 \rfloor (S) = \{ V \mid \text{ there exist } V_1 \in \llbracket \varphi_1 \rfloor (S), V_2 \in \llbracket \varphi_2 \rfloor (S)$$

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$\llbracket \varphi_1; \varphi_2 \rfloor (S) = \{ V \mid \text{ there exist } V_1 \in \llbracket \varphi_1 \rfloor (S), V_2 \in \llbracket \varphi_2 \rfloor (S) \text{ s.t. } V_1(\text{end}) < V_2(\text{start}) \}$$

$$R \qquad \varphi; \varphi \qquad \varphi \text{ DR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$\llbracket \varphi_1; \varphi_2 \rfloor (S) = \{ V \mid \text{ there exist } V_1 \in \llbracket \varphi_1 \rfloor (S), V_2 \in \llbracket \varphi_2 \rfloor (S) \text{ s.t. } V_1(\text{end}) < V_2(\text{start}) \\ \land \quad V(\text{time}) = [V_1(\text{start}), V_2(\text{end})]$$

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$\llbracket \varphi_1; \varphi_2 \rfloor (S) = \{ V \mid \text{ there exist } V_1 \in \llbracket \varphi_1 \rfloor (S), V_2 \in \llbracket \varphi_2 \rfloor (S) \text{ s.t. } V_1(\text{end}) < V_2(\text{start}) \\ \land \quad V(\text{time}) = [V_1(\text{start}), V_2(\text{end})] \\ \land \quad \forall X. \quad V(X) = V_1(X) \cup V_2(X) \}$$

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$\llbracket \varphi_1; \varphi_2 \rfloor (S) = \{ V \mid \text{ there exist } V_1 \in \llbracket \varphi_1 \rfloor (S), V_2 \in \llbracket \varphi_2 \rfloor (S) \text{ s.t. } V_1(\text{end}) < V_2(\text{start}) \\ \land \quad V(\text{time}) = [V_1(\text{start}), V_2(\text{end})] \\ \land \quad \forall X. \quad V(X) = V_1(X) \cup V_2(X) \}$$

Example:
$$\varphi = B$$
; S
 S : B_0 B_1 S_2 B_3 S_4 S_5 S_6 B_7 B_8 B_9 \cdots
 $\llbracket \varphi \rrbracket (S)$:

$$R \qquad \varphi; \varphi \qquad \varphi \text{ DR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$\llbracket \varphi_1; \varphi_2 \rrbracket (S) = \{ V \mid \text{ there exist } V_1 \in \llbracket \varphi_1 \rrbracket (S), V_2 \in \llbracket \varphi_2 \rrbracket (S) \text{ s.t. } V_1(\text{end}) < V_2(\text{start}) \\ \land \qquad V(\text{time}) = [V_1(\text{start}), V_2(\text{end})] \\ \land \qquad \forall X. \quad V(X) = V_1(X) \cup V_2(X) \}$$

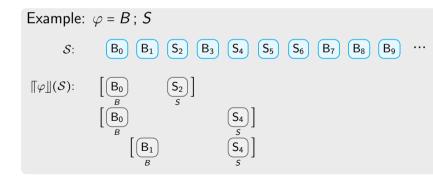
Example:
$$\varphi = B$$
; S
S: B₀ B₁ S₂ B₃ S₄ S₅ S₆ B₇ B₈ B₉ ...
 $\llbracket \varphi \rfloor (S)$: $\begin{bmatrix} B_0 & S_2 \\ B & S_2 \end{bmatrix}$

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$\llbracket \varphi_1; \varphi_2 \rrbracket (S) = \{ V \mid \text{ there exist } V_1 \in \llbracket \varphi_1 \rrbracket (S), V_2 \in \llbracket \varphi_2 \rrbracket (S) \text{ s.t. } V_1(\text{end}) < V_2(\text{start}) \\ \land \quad V(\text{time}) = [V_1(\text{start}), V_2(\text{end})] \\ \land \quad \forall X. \quad V(X) = V_1(X) \cup V_2(X) \}$$

Example:
$$\varphi = B$$
; S
 $S: \quad B_0 \quad B_1 \quad S_2 \quad B_3 \quad S_4 \quad S_5 \quad S_6 \quad B_7 \quad B_8 \quad B_9 \quad \cdots$

$$\left[\varphi \rfloor (S): \quad \begin{bmatrix} B_0 & S_2 \\ B_0 & S_2 \end{bmatrix} \right]_{\left[\begin{array}{c} B \\ B_0 \\ B \end{array} \right]} \quad S_4 \quad S_5 \quad S_6 \quad B_7 \quad B_8 \quad B_9 \quad \cdots$$

$$R \qquad \varphi; \varphi \qquad \varphi \ \mathsf{OR} \ \varphi \ \varphi + \varphi \ \mathsf{AS} \ X \qquad \varphi \ \mathsf{FILTER} \ P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$\llbracket \varphi_1; \varphi_2 \rfloor (\mathcal{S}) = \{ V \mid \mathsf{there exist} \ V_1 \in \llbracket \varphi_1 \rfloor (\mathcal{S}), V_2 \in \llbracket \varphi_2 \rfloor (\mathcal{S}) \ \mathsf{s.t.} \ V_1(\mathsf{end}) < V_2(\mathsf{start}) \\ \land \ V(\mathsf{time}) = [V_1(\mathsf{start}), V_2(\mathsf{end})] \\ \land \ \forall X. \ V(X) = V_1(X) \cup V_2(X) \}$$



$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$

 $R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \qquad \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$ $\llbracket \varphi_1 \text{ OR } \varphi_2 \rrbracket (\mathcal{S}) \qquad = \llbracket \varphi_1 \rrbracket (\mathcal{S}) \cup \llbracket \varphi_2 \rrbracket (\mathcal{S})$

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \qquad \varphi \text{ AS } X \qquad \varphi \text{ filter } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$

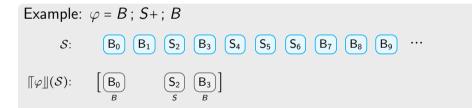
$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$\llbracket \varphi + \rfloor (S) = \bigcup_{k=1}^{\infty} \llbracket \varphi^k \rfloor (S) \text{ where } \varphi^k = \varphi; \cdots; \varphi \text{ } k \text{-times}$$

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$\llbracket \varphi + \rfloor (S) = \bigcup_{k=1}^{\infty} \llbracket \varphi^k \rfloor (S) \text{ where } \varphi^k = \varphi; \cdots; \varphi \text{ } k \text{-times}$$

Example: $\varphi = B$; S + ; B $S: \quad B_0 \quad B_1 \quad S_2 \quad B_3 \quad S_4 \quad S_5 \quad S_6 \quad B_7 \quad B_8 \quad B_9 \quad \cdots$

 $\llbracket \varphi
rbracket (S)$:

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$\llbracket \varphi + \rfloor (S) = \bigcup_{k=1}^{\infty} \llbracket \varphi^k \rfloor (S) \text{ where } \varphi^k = \varphi; \cdots; \varphi \text{ } k \text{-times}$$



$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$\llbracket \varphi + \rfloor (S) = \bigcup_{k=1}^{\infty} \llbracket \varphi^k \rfloor (S) \text{ where } \varphi^k = \varphi; \cdots; \varphi \text{ } k \text{-times}$$

Example:
$$\varphi = B$$
; $S + ; B$
 $S: \quad B_0 \quad B_1 \quad S_2 \quad B_3 \quad S_4 \quad S_5 \quad S_6 \quad B_7 \quad B_8 \quad B_9 \quad \cdots$
 $\llbracket \varphi \rfloor (S): \quad \begin{bmatrix} B_0 & S_2 & B_3 \end{bmatrix}_{\substack{B \\ B_0 & S_2 & S_3 \\ B} \quad S_4 \quad S_5 \quad S_6 \quad B_7 \end{bmatrix}_{B}$

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$\llbracket \varphi + \rfloor (S) = \bigcup_{k=1}^{\infty} \llbracket \varphi^k \rfloor (S) \text{ where } \varphi^k = \varphi; \cdots; \varphi \text{ } k \text{-times}$$

Example:
$$\varphi = B$$
; $S + ; B$
 $S: B_0 B_1 S_2 B_3 S_4 S_5 S_6 B_7 B_8 B_9 \cdots$
 $\|\varphi\|(S): \begin{bmatrix} B_0 & S_2 & B_3 \end{bmatrix}$
 $\begin{bmatrix} B_0 & S_2 & B_3 \end{bmatrix}$
 $\begin{bmatrix} B_0 & S_2 & B_3 \end{bmatrix}$
 $\begin{bmatrix} B_0 & S_2 & S_3 & S_4 & S_5 & S_6 & B_7 \end{bmatrix}$
 $\begin{bmatrix} B_0 & S_2 & S_3 & S_4 & S_5 & S_6 & B_7 \end{bmatrix}$
 $\begin{bmatrix} B_0 & S_2 & S_3 & S_5 & S_6 & B_7 \end{bmatrix}$

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \qquad \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$

$$R \qquad \varphi; \varphi \qquad \varphi \ \text{OR} \ \varphi \qquad \varphi + \qquad \varphi \ \text{AS } X \qquad \varphi \ \text{FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$[\![\varphi \ \text{AS } X]\!](S) = \{V \mid \exists V' \in [\![\varphi]\!](S). \ V(\text{time}) = V'(\text{time}) \\ \land V(X) = \bigcup_{Y} V'(Y) \\ \land \forall Z \neq X. \ V(Z) = V'(Z) \}$$

$$R \qquad \varphi; \varphi \qquad \varphi \ \text{OR} \ \varphi \qquad \varphi + \qquad \varphi \ \text{AS } X \qquad \varphi \ \text{FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$[\![\varphi \ \text{AS } X \rfloor\!](S) = \{V \mid \exists V' \in [\![\varphi]\!](S). \ V(\text{time}) = V'(\text{time}) \\ \land V(X) = \bigcup_Y V'(Y) \\ \land \forall Z \neq X. \ V(Z) = V'(Z) \}$$

Example:
$$\varphi = (B; S+)$$
; B
S: B_0 B_1 S_2 B_3 S_4 S_5 S_6 B_7 B_8 B_9 ...
 $\llbracket \varphi \rfloor (S)$: $\begin{bmatrix} B_0 & S_2 & B_3 \end{bmatrix}$
 $\begin{bmatrix} B_0 & S_2 & B_3 \end{bmatrix}$
 $\begin{bmatrix} B_0 & S_2 & S_4 & S_5 & S_6 & B_7 \end{bmatrix}$
 $\begin{bmatrix} B_0 & S_2 & S_4 & S_5 & S_6 & B_7 \end{bmatrix}$
 $\begin{bmatrix} B_0 & S_2 & S_4 & S_5 & S_6 & B_7 \end{bmatrix}$
 $\begin{bmatrix} B_0 & S_2 & S_4 & S_5 & S_6 & B_7 \end{bmatrix}$

$$\begin{split} \llbracket \varphi \rrbracket (\mathcal{S}) &: \begin{bmatrix} B_0 & & S_2 & B_3 \\ B, \chi & & S_2 & B_3 \\ \begin{bmatrix} B_0 & & S_2 & & S_4 & S_5 & S_6 & B_7 \\ B, \chi & & S, \chi & & S, \chi & S, \chi & B_7 \\ \end{bmatrix} \\ \begin{bmatrix} B_0 & & S_2 & & S_5 & & B_7 \\ B, \chi & & S, \chi & & S, \chi & B_7 \end{bmatrix} \\ \end{split}$$

- 5

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ filter } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi^+ \qquad \varphi \text{ AS } X \qquad \varphi \text{ filter } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$

Definition

Consider universal predicates $P(X_1, \ldots, X_n)$ of the form:

 $P(X_1,\ldots,X_n) := \forall t_1 \in X_1 \ldots \forall t_n \in X_n. P_E(t_1,\ldots,t_n)$

where $P_E(t_1, \ldots, t_n)$ is a first-order predicate over tuples.

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ filter } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$

Definition

Consider universal predicates $P(X_1, \ldots, X_n)$ of the form:

$$P(X_1,\ldots,X_n) := \forall t_1 \in X_1 \ldots \forall t_n \in X_n. P_E(t_1,\ldots,t_n)$$

where $P_E(t_1, \ldots, t_n)$ is a first-order predicate over tuples. Examples

Stock=a(X) := $\forall t \in X. t[stock] = 'a'$

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi^+ \qquad \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$

Definition

Consider universal predicates $P(X_1, \ldots, X_n)$ of the form:

$$P(X_1,\ldots,X_n) := \forall t_1 \in X_1 \ldots \forall t_n \in X_n. P_E(t_1,\ldots,t_n)$$

where $P_E(t_1, ..., t_n)$ is a first-order predicate over tuples. Examples

Stock=a(X) :=
$$\forall t \in X. t[stock] = a$$

SameStock $(X_1, X_2) := \forall t_1 \in X_1. \forall t_2 \in X_2. t_1[\text{stock}] = t_2[\text{stock}]$

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi^+ \qquad \varphi \text{ AS } X \qquad \varphi \text{ filter } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$

Definition

Consider universal predicates $P(X_1, \ldots, X_n)$ of the form:

$$P(X_1,\ldots,X_n) := \forall t_1 \in X_1 \ldots \forall t_n \in X_n. P_E(t_1,\ldots,t_n)$$

where $P_E(t_1,...,t_n)$ is a first-order predicate over tuples. Examples

Stock=
$$a(X) := \forall t \in X. t[stock] = 'a'$$

SameStock $(X_1, X_2) \coloneqq \forall t_1 \in X_1. \forall t_2 \in X_2. t_1[\text{stock}] = t_2[\text{stock}]$

The definition of CEL considers any predicate over tuples of sets of events but we restrict to **universal predicates** to fit our purposes.

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ filter } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$

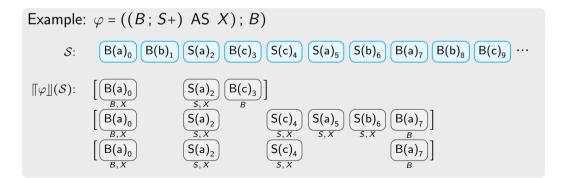
$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \qquad \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$\left[\varphi \text{ FILTER } P(\overline{X}) \right] (S) \qquad = \{ V \mid V \in \left[\varphi \right] (S) \land V(\overline{X}) \in P \}$$

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \qquad \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$[\![\varphi \text{ FILTER } P(\overline{X})]\!](S) = \{V \mid V \in [\![\varphi]](S) \land V(\overline{X}) \in P \}$$

Example: $\varphi = ((B; S+) AS X); B)$ $\mathcal{S}: \qquad B(a)_0 B(b)_1 S(a)_2 B(c)_3 S(c)_4 S(a)_5 S(b)_6 B(a)_7 B(b)_8 B(c)_9 \cdots$

 $\llbracket \varphi
rbracket (\mathcal{S})$:

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \qquad \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$[\![\varphi \text{ FILTER } P(\overline{X})]\!](S) = \{V \mid V \in [\![\varphi]](S) \land V(\overline{X}) \in P \}$$



$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \qquad \varphi \text{ AS } X \qquad \varphi \text{ FILTER } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$
$$[[\varphi \text{ FILTER } P(\overline{X})]](S) = \{V \mid V \in [[\varphi]](S) \land V(\overline{X}) \in P \}$$

Example: $\varphi = ((B; S+) AS X); B)$ FILTER Stock=a(X) $[B(b)_1]$ $[S(a)_2]$ $[B(c)_3]$ $[S(c)_4]$ $[S(a)_5]$ $[S(b)_6]$ $[B(a)_7]$ $[B(b)_8]$ $[B(c)_9]$ \mathcal{S} : $B(a)_0$. . . $\llbracket \varphi \rrbracket (\mathcal{S})$: $|B(a)_0|$ $S(a)_2$ B(c)₃ 5. X R X B(a)₀ **S(a)**₂ S(a)S(a)S(h) B(a)10/6 B.X 5. X 5. X 5. X S, XВ S(-) S(c) $S(a)_2$ $S(c)_4$ $D(u)_7$ B, XS, XS, XR

$$R \qquad \varphi; \varphi \qquad \varphi \text{ OR } \varphi \qquad \varphi + \varphi \text{ AS } X \qquad \varphi \text{ filter } P(\overline{X}) \qquad \pi_{\overline{X}}(\varphi)$$

Example: $\varphi = ((B; S+) AS X); B)$ FILTER Stock=a(X) $\mathcal{S}: \quad B(a)_0 B(b)_1 S(a)_2 B(c)_3 S(c)_4 S(a)_5 S(b)_6 B(a)_7 B(b)_8 B(c)_9 \cdots$

 $\llbracket \varphi
rbracket (\mathcal{S})$:

Example:
$$\varphi = ((B; S+) AS X); B)$$
 FILTER Stock=a(X)
 $S: B(a)_0 B(b)_1 S(a)_2 B(c)_3 S(c)_4 S(a)_5 S(b)_6 B(a)_7 B(b)_8 B(c)_9 \cdots$
 $\|\varphi\|(S): \begin{bmatrix} B(a)_0 & S(a)_2 & S(a)_5 & B(a)_7 \\ B,X & S,X & S(a)_5 & B(a)_7 \\ B,X & S,X & B(a)_7 \\ B,X & S(a)_7 & S(a)_7 \\ B,X & S(a)$

CEL semantics (final)

The **output** of a CEL formula φ over a stream S at **position** *n* is defined as:

$$\llbracket \varphi \rrbracket_n(\mathcal{S}) = \left\{ \left(V(\mathsf{time}), \bigcup_X V(X) \right) \mid V \in \llbracket \varphi \rrbracket(\mathcal{S}), V(\mathsf{end}) = n \right\}$$

CEL semantics (final)

The **output** of a CEL formula φ over a stream S at **position** *n* is defined as:

$$\llbracket \varphi \rrbracket_n(\mathcal{S}) = \left\{ \left(V(\mathsf{time}), \bigcup_X V(X) \right) \mid V \in \llbracket \varphi \rrbracket(\mathcal{S}), V(\mathsf{end}) = n \right\}$$

All complex events that satisfy the formula are given as output

Selection strategies

CER systems includes operations to filter complex events:

Selection strategies

usually defined by an algorithm.

Selection strategies

CER systems includes operations to filter complex events:

Selection strategies

usually defined by an algorithm.

Example: skip-till-next-match in SASE

"a further relaxation is to remove the contiguity requirements: all irrelevant events will be skipped until the next relevant event is read." [1]

[1] D. Gyllstrom, J. Agrawal, Y. Diao, and N. Immerman "On supporting Kleene closure over event streams", ICDE 2008.

Selection strategies

CER systems includes operations to filter complex events:

Selection strategies

usually defined by an algorithm.

Example: skip-till-next-match in SASE

"a further relaxation is to remove the contiguity requirements: all irrelevant events will be skipped until the next relevant event is read." [1]

In CEL we declaratively formalize existing selection strategies, and propose new ones [2].

[1] D. Gyllstrom, J. Agrawal, Y. Diao, and N. Immerman

- "On supporting Kleene closure over event streams", ICDE 2008.
- [2] A. Grez, C. Riveros, M. Ugarte, and S. Vansummeren
- "A Formal Framework for Complex Event Recognition", ACM TODS 46(4), 2021.

Outline

A logic for CER

An automaton model for CER

Evaluation algorithm

The CORE complex event recognition engine

Open questions

Complex event automata

Let P_1 be the set of all unary predicates over tuples.

Complex event automata

Let P_1 be the set of all unary predicates over tuples.

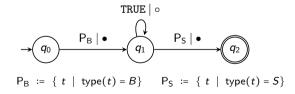
Definition

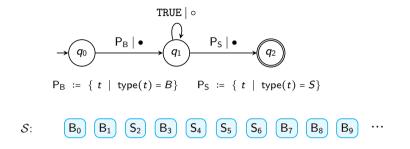
A complex event automata (CEA) is a tuple $\mathcal{A} = (Q, \Delta, I, F)$ where:

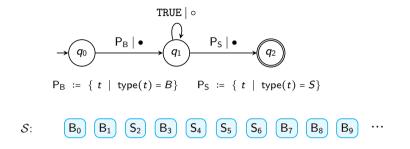
1. Q is a finite set of states,

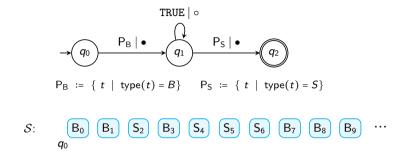
2. I and F are the sets of initial and final states, and

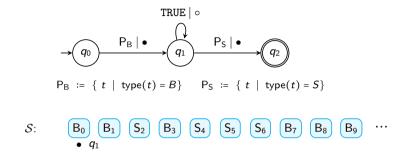
3. $\Delta \subseteq Q \times P_1 \times \{\bullet, \circ\} \times Q$ is the transition relation.

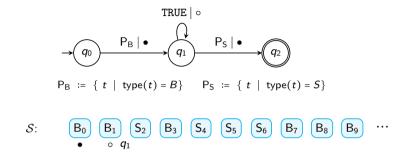


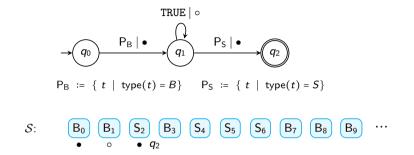


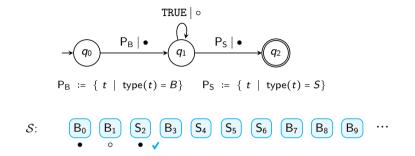


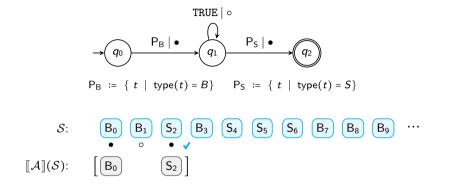


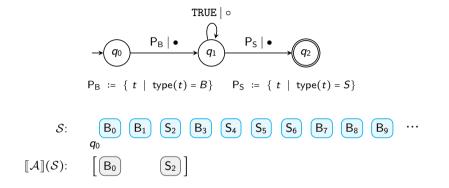


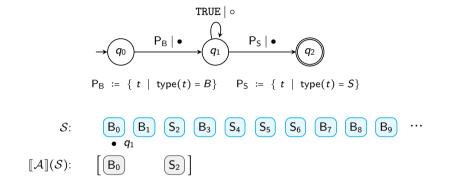


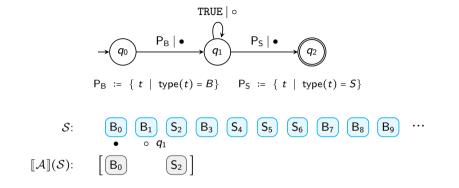


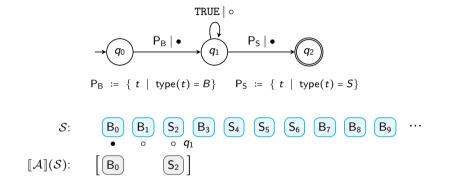


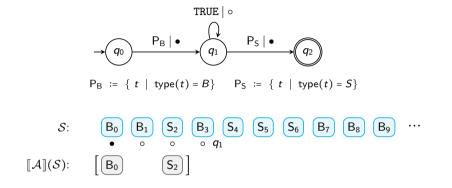


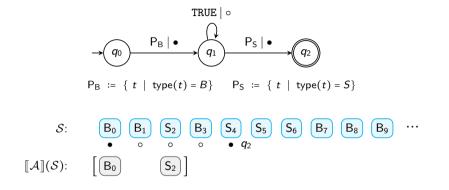


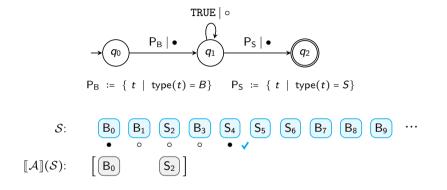


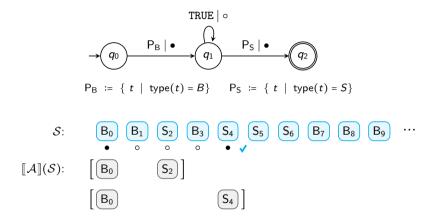


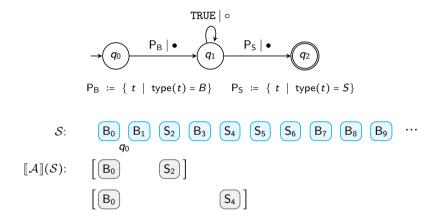


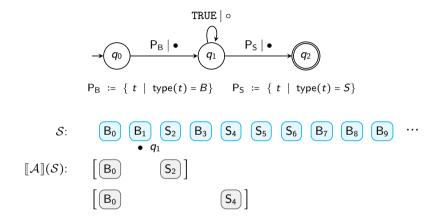


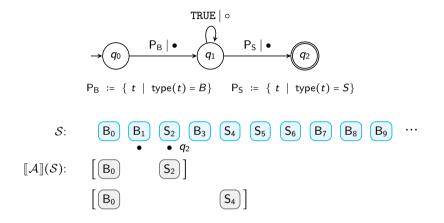


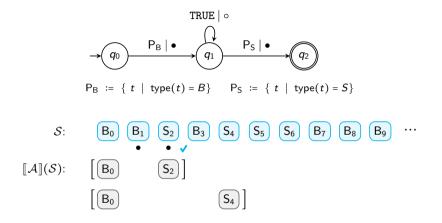


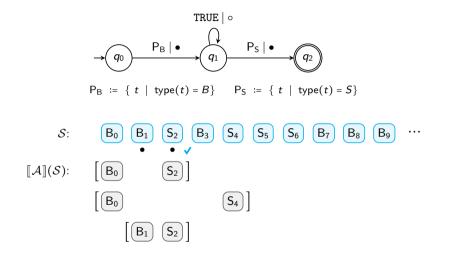


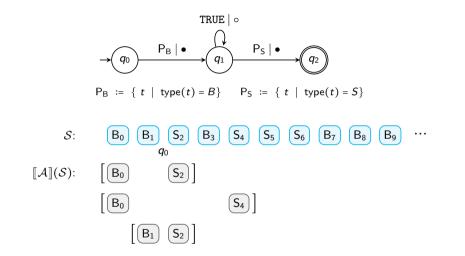


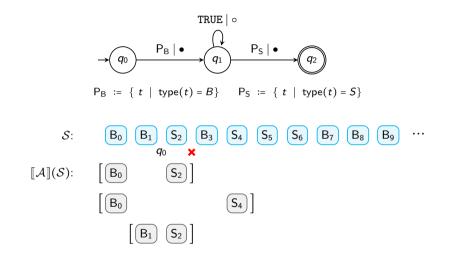












Theorem

For every CEL-formula φ with unary predicate filters we can construct a CEA A of size linear in φ s.t.

 $\llbracket \varphi \rrbracket_n(S) = \llbracket \mathcal{A} \rrbracket_n(S)$ for every stream S and position n.

Theorem

For every CEL-formula φ with unary predicate filters we can construct a CEA A of size linear in φ s.t.

 $\llbracket \varphi \rrbracket_n(S) = \llbracket A \rrbracket_n(S)$ for every stream S and position n.

• CEA form a model of the "regular fragment" of CER queries.

Theorem

For every CEL-formula φ with unary predicate filters we can construct a CEA A of size linear in φ s.t.

 $\llbracket \varphi \rrbracket_n(S) = \llbracket A \rrbracket_n(S)$ for every stream S and position n.

• CEA form a model of the "regular fragment" of CER queries.

Selection strategies can be encoded in the automaton model, see [1].

Theorem

For every CEL-formula φ with unary predicate filters we can construct a CEA A of size linear in φ s.t.

$$\llbracket \varphi \rrbracket_n(S) = \llbracket A \rrbracket_n(S)$$
 for every stream S and position n.

- CEA form a model of the "regular fragment" of CER queries.
- Selection strategies can be encoded in the automaton model, see [1].
- CEL can be extended to capture the expressive power of CEA, see [1].

 A. Grez, C. Riveros, M. Ugarte, and S. Vansummeren "A Formal Framework for Complex Event Recognition", ACM TODS 46(4), 2021.

Outline

A logic for CER

An automaton model for CER

Evaluation algorithm

The CORE complex event recognition engine

Open questions

The partial match problem in current engines

- FROM StockMarketStream
- PATTERN BUY b1, BUY b2, ... , BUY bk WITHIN 10 seconds
- RETURN b1, b2, ..., bk

(Written in SASE+ language)

The partial match problem in current engines

FROM StockMarketStream
PATTERN BUY b1, BUY b2, ..., BUY bk
WITHIN 10 seconds
RETURN b1, b2, ..., bk

(Written in SASE+ language)

--- Esper --- FlinkCEP --- SASE --- OpenCEP Stock Market 10^{7} Throughput (e/s) 10^{6} 10^{5} 10^{4} 10³ 10² 10^1 3 6 9 12 24 Sequence length (k)

Main idea

"Separate the streaming evaluation of CEA ${\mathcal A}$ into two processes"

Main idea

"Separate the streaming evaluation of CEA ${\mathcal A}$ into two processes"

1. Update on each event

Main idea

"Separate the streaming evaluation of CEA ${\mathcal A}$ into two processes"

1. Update on each event

• We keep a compact representation *T* of partial outputs (runs).

Main idea

"Separate the streaming evaluation of CEA ${\mathcal A}$ into two processes"

1. Update on each event

- We keep a compact representation *T* of partial outputs (runs).
- For each new event e, we take linear time |e| + |A| to update T, independently of |T|.

Main idea

"Separate the streaming evaluation of CEA ${\mathcal A}$ into two processes"

1. Update on each event

- We keep a compact representation T of partial outputs (runs).
- For each new event e, we take linear time |e| + |A| to update T, independently of |T|.
- 2. Enumeration of outputs (output-linear delay enumeration)

Main idea

"Separate the streaming evaluation of CEA ${\mathcal A}$ into two processes"

1. Update on each event

- We keep a compact representation T of partial outputs (runs).
- For each new event e, we take linear time |e| + |A| to update T, independently of |T|.

2. Enumeration of outputs (output-linear delay enumeration)

• Whenever an event triggers new recognized complex events, the enumeration phase is called, independent of the update process.

Main idea

"Separate the streaming evaluation of CEA ${\mathcal A}$ into two processes"

1. Update on each event

- We keep a compact representation T of partial outputs (runs).
- For each new event e, we take linear time |e| + |A| to update T, independently of |T|.
- 2. Enumeration of outputs (output-linear delay enumeration)
 - Whenever an event triggers new recognized complex events, the enumeration phase is called, independent of the update process.
 - All complex events C₁, C₂,... for the current position are enumerated taking O(|C_i|) time to print C_i.

Main idea

"Separate the streaming evaluation of CEA ${\mathcal A}$ into two processes"

1. Update on each event

"Same guarantee as a streaming algorithm."

2. Enumeration of outputs (output-linear delay enumeration)

- Whenever an event triggers new recognized complex events, the enumeration phase is called, independent of the update process.
- All complex events C₁, C₂,... for the current position are enumerated taking O(|C_i|) time to print C_i.

Main idea

"Separate the streaming evaluation of CEA ${\mathcal A}$ into two processes"

1. Update on each event

"Same guarantee as a streaming algorithm."

2. Enumeration of outputs (output-linear delay enumeration)

"Users do not see any difference compared to naively storing all outputs"

Main idea

"Separate the streaming evaluation of CEA ${\mathcal A}$ into two processes"

1. Update on each event

"Same guarantee as a streaming algorithm."

2. Enumeration of outputs (output-linear delay enumeration)

"Users do not see any difference compared to naively storing all outputs"

If an evaluation algorithm E satisfies 1. and 2., we say that E has **output-linear delay** evaluation.

CEA evaluation strategy

Definition Let $\epsilon \in \mathbb{N} \cup \{\infty\}$, let \mathcal{A} be a CEA and \mathcal{S} a stream. We define

 $\llbracket \mathcal{A} \text{ WITHIN } \epsilon \rrbracket(\mathcal{S}) \coloneqq \{ C \in \llbracket \mathcal{A} \rrbracket(\mathcal{S}) \mid C(\mathsf{end}) - C(\mathsf{start}) \leq \epsilon \}.$

CEA evaluation strategy

Theorem

 $\llbracket \mathcal{A} \text{ WITHIN } \epsilon \rrbracket \text{ can be evaluated with output-linear delay, for every CEA } \mathcal{A} \text{ and every } \epsilon.$

CEA evaluation strategy

Theorem

 $\llbracket \mathcal{A} \text{ WITHIN } \epsilon \rrbracket \text{ can be evaluated with output-linear delay, for every CEA } \mathcal{A} \text{ and every } \epsilon.$

Main ideas of the algorithm:

1. A notion of I/O deterministic CEA.

CEA evaluation strategy

Theorem

 $\llbracket \mathcal{A} \text{ WITHIN } \epsilon \rrbracket$ can be evaluated with output-linear delay, for every CEA \mathcal{A} and every ϵ .

Main ideas of the algorithm:

- 1. A notion of I/O deterministic CEA.
- 2. A timed Enumerable Compact Set (tECS) for compactly representing complex events and enumerating all outputs with window-size ϵ .

CEA evaluation strategy

Theorem

 $\llbracket \mathcal{A} \text{ WITHIN } \epsilon \rrbracket$ can be evaluated with **output-linear delay**, for every CEA \mathcal{A} and every ϵ .

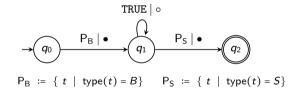
Main ideas of the algorithm:

- 1. A notion of I/O deterministic CEA.
- 2. A timed Enumerable Compact Set (tECS) for compactly representing complex events and enumerating all outputs with window-size ϵ .
- 3. An evaluation algorithm for incrementally building tECS given active states of I/O deterministic CEA.

I/O determinism

Definition

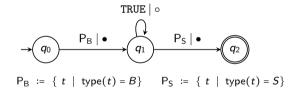
A CEA is I/O deterministic if for every pair of transitions $q \xrightarrow{P_1/m_1} q_1$ and $q \xrightarrow{P_2/m_2} q_2$ from the same state q, if $P_1 \cap P_2 \neq \emptyset$ then $m_1 \neq m_2$.



I/O determinism

Definition

A CEA is I/O deterministic if for every pair of transitions $q \xrightarrow{P_1/m_1} q_1$ and $q \xrightarrow{P_2/m_2} q_2$ from the same state q, if $P_1 \cap P_2 \neq \emptyset$ then $m_1 \neq m_2$.

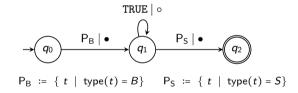


"Every recognized complex event has only one run that defines it."

I/O determinism

Definition

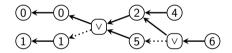
A CEA is I/O deterministic if for every pair of transitions $q \xrightarrow{P_1/m_1} q_1$ and $q \xrightarrow{P_2/m_2} q_2$ from the same state q, if $P_1 \cap P_2 \neq \emptyset$ then $m_1 \neq m_2$.



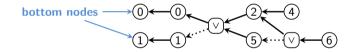
Proposition

CEA can be I/O-determinized in exponential time.

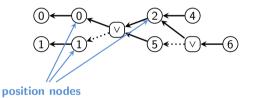
Definition



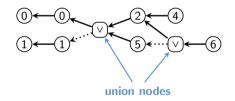
Definition



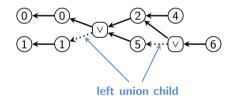
Definition



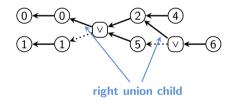
Definition



Definition



Definition



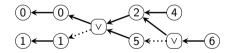
Definition

A open complex event is a pair (i, C) with $i \in \mathbb{N}$ and $C \subseteq \mathbb{N}$ finite.

Definition

A open complex event is a pair (i, C) with $i \in \mathbb{N}$ and $C \subseteq \mathbb{N}$ finite.

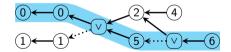
- Every path from a node to a bottom node defines an open complex event.
- A node *n* hence encodes a set [n] of open complex events.



Definition

A open complex event is a pair (i, C) with $i \in \mathbb{N}$ and $C \subseteq \mathbb{N}$ finite.

- Every path from a node to a bottom node defines an open complex event.
- A node *n* hence encodes a set [*n*] of open complex events.

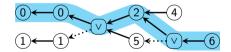


Open complex event: $(0, \{0, 5, 6\})$

Definition

A open complex event is a pair (i, C) with $i \in \mathbb{N}$ and $C \subseteq \mathbb{N}$ finite.

- Every path from a node to a bottom node defines an open complex event.
- A node *n* hence encodes a set [*n*] of open complex events.

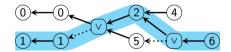


Open complex event: $(0, \{0, 2, 6\})$

Definition

A open complex event is a pair (i, C) with $i \in \mathbb{N}$ and $C \subseteq \mathbb{N}$ finite.

- Every path from a node to a bottom node defines an open complex event.
- A node *n* hence encodes a set [*n*] of open complex events.

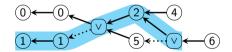


Open complex event: $(1, \{1, 2, 6\})$

Definition

A open complex event is a pair (i, C) with $i \in \mathbb{N}$ and $C \subseteq \mathbb{N}$ finite.

- Every path from a node to a bottom node defines an open complex event.
- A node *n* hence encodes a set [*n*] of open complex events.



Open complex event: $(1, \{1, 2\})$

For each position node *n*, window size ϵ and $j \in \mathbb{N}$ we want to be able to enumerate

 $\llbracket n \rrbracket^{\epsilon}(j) \coloneqq \{ \qquad | (i, C) \in \llbracket n \rrbracket \}$

For each position node *n*, window size ϵ and $j \in \mathbb{N}$ we want to be able to enumerate

 $\llbracket n \rrbracket^{\epsilon}(j) := \{ \qquad | (i, C) \in \llbracket n \rrbracket, \ j - i \le \epsilon \}$

For each position node *n*, window size ϵ and $j \in \mathbb{N}$ we want to be able to enumerate

 $\llbracket n \rrbracket^{\epsilon}(j) \coloneqq \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$

For each position node *n*, window size ϵ and $j \in \mathbb{N}$ we want to be able to enumerate

 $\llbracket n \rrbracket^{\epsilon}(j) \coloneqq \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$

with output-linear delay.

For each position node *n*, window size ϵ and $j \in \mathbb{N}$ we want to be able to enumerate

 $\llbracket n \rrbracket^{\epsilon}(j) \coloneqq \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$

with output-linear delay.

In order to allow this, we need the following structure on tECS:

For every node *n*, distinct paths starting at *n* encode distinct open complex events.

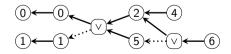
For each position node *n*, window size ϵ and $j \in \mathbb{N}$ we want to be able to enumerate

 $\llbracket n \rrbracket^{\epsilon}(j) \coloneqq \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$

with output-linear delay.

In order to allow this, we need the following structure on tECS:

For every node *n*, distinct paths starting at *n* encode distinct open complex events.

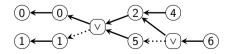


For each position node *n*, window size ϵ and $j \in \mathbb{N}$ we want to be able to enumerate

 $\llbracket n \rrbracket^{\epsilon}(j) \coloneqq \{ (\llbracket i, j \rrbracket, C) \mid (i, C) \in \llbracket n \rrbracket, \ j - i \le \epsilon \}$

with output-linear delay.

- For every node *n*, distinct paths starting at *n* encode distinct open complex events.
- Nodes store their max-start time: the largest time value of any bottom node reachable from *n*.

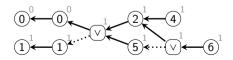


For each position node *n*, window size ϵ and $j \in \mathbb{N}$ we want to be able to enumerate

 $\llbracket n \rrbracket^{\epsilon}(j) \coloneqq \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$

with output-linear delay.

- For every node *n*, distinct paths starting at *n* encode distinct open complex events.
- Nodes store their max-start time: the largest time value of any bottom node reachable from *n*.

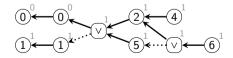


For each position node *n*, window size ϵ and $j \in \mathbb{N}$ we want to be able to enumerate

 $\llbracket n \rrbracket^{\epsilon}(j) \coloneqq \{ (\llbracket i, j \rrbracket, C) \mid (i, C) \in \llbracket n \rrbracket, \ j - i \le \epsilon \}$

with output-linear delay.

- For every node *n*, distinct paths starting at *n* encode distinct open complex events.
- Nodes store their max-start time: the largest time value of any bottom node reachable from *n*.
- The children of union nodes u are max-start sorted: $\max(\operatorname{left}(u)) \ge \max(\operatorname{right}(u))$.

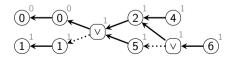


For each position node *n*, window size ϵ and $j \in \mathbb{N}$ we want to be able to enumerate

 $\llbracket n \rrbracket^{\epsilon}(j) \coloneqq \{ (\llbracket i, j \rrbracket, C) \mid (i, C) \in \llbracket n \rrbracket, \ j - i \le \epsilon \}$

with output-linear delay.

- For every node *n*, distinct paths starting at *n* encode distinct open complex events.
- Nodes store their max-start time: the largest time value of any bottom node reachable from *n*.
- The children of union nodes u are max-start sorted: $\max(\operatorname{left}(u)) \ge \max(\operatorname{right}(u))$.
- There is a constant bounding the length of chains of union left-child paths.



Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

with output-linear delay.

Example: n = 6, $\epsilon = 5$, j = 6 $0^{\circ} \qquad 0^{\circ} \qquad$

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.

Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

with output-linear delay.

Example: n = 6, $\epsilon = 5$, j = 6 $0^{0} \qquad 0^{0} \qquad 0^{1} \qquad 2^{1} \qquad 4^{1} \qquad 0^{1} \qquad$

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.

Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

with output-linear delay.

Example: n = 6, $\epsilon = 5$, j = 6 $0 \leftarrow 0 \leftarrow 1 \leftarrow 2 \leftarrow 4 \leftarrow 1$ $1 \leftarrow 1 \leftarrow 0 \leftarrow 5 \leftarrow 0 \leftarrow 6$

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.

Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

with output-linear delay.

Example:
$$n = 6$$
, $\epsilon = 5$, $j = 6$

$$0^{\circ} \qquad 0^{\circ} \qquad$$

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.

Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

with output-linear delay.

Example: n = 6, $\epsilon = 5$, j = 6 $0^{\circ} \qquad 0^{\circ} \qquad$

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.

Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

with output-linear delay.

Example: n = 6, $\epsilon = 5$, j = 6

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.

Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

with output-linear delay.

Example: n = 6, $\epsilon = 5$, j = 6output ([1,6], {1,5,6})

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.

Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

with output-linear delay.

Example: n = 6, $\epsilon = 5$, j = 6

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.

Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

with output-linear delay.

Example: n = 6, $\epsilon = 5$, j = 6 $0^{\circ} \qquad 0^{\circ} \qquad$

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.

Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

with output-linear delay.

Example:
$$n = 6$$
, $\epsilon = 5$, $j = 6$

$$0^{\circ} \qquad 0^{\circ} \qquad$$

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.

Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

with output-linear delay.

Example: n = 6, $\epsilon = 5$, j = 6 $0 \leftarrow 0 \leftarrow 1 \leftarrow 2 \leftarrow 4 \leftarrow 1$ $1 \leftarrow 1 \leftarrow 0 \leftarrow 5 \leftarrow 0 \leftarrow 6$

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.

Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

with output-linear delay.

Example:
$$n = 6$$
, $\epsilon = 5$, $j = 6$

$$0^{0} + 0^{0} + 2^{1} + 2^{1} + 4^{1}$$

$$1^{1} + 1^{1} + \cdots + 5^{1} + \cdots + 5^{1} + 1^{1} + 5^{1} + \cdots + 5^{1} + 5^{1} + 1^{1} + 5^{1$$

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.

Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

with output-linear delay.

Example: n = 6, $\epsilon = 5$, j = 6 $0 \leftarrow 0 \leftarrow 0 \leftarrow 2 \leftarrow 4 \leftarrow 1$ $1 \leftarrow 1 \leftarrow 0 \leftarrow 5 \leftarrow 0 \leftarrow 1$

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.

Theorem

Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ ([i,j], C) \mid (i, C) \in \llbracket n \rrbracket, \ j-i \le \epsilon \}$$

with output-linear delay.

Example: n = 6, $\epsilon = 5$, j = 6

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.

Theorem

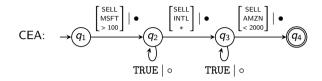
Under the previous conditions, we may enumerate

$$\llbracket n \rrbracket^{\epsilon}(j) = \{ (\llbracket i, j \rrbracket, C) \mid (i, C) \in \llbracket n \rrbracket, \ j - i \le \epsilon \}$$

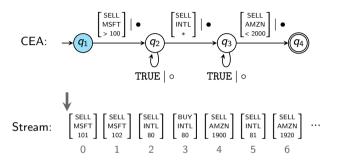
with output-linear delay.

Example: n = 6, $\epsilon = 5$, j = 6output ([1,6], {1,2,6})

- Do depth-first search, starting from *n*.
- Visit left-children of union nodes before right-children.
- Before moving to a child c, check that $j \max(c) \le \epsilon$.



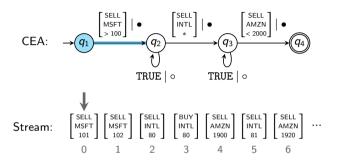




Algorithm crux:

Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.

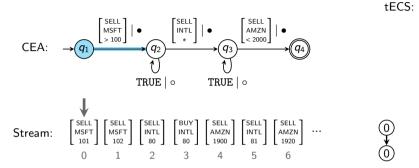
tECS:



Algorithm crux:

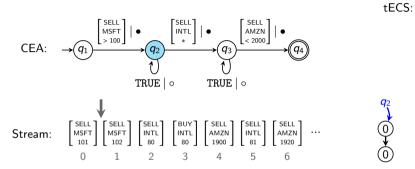
Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.

tECS:

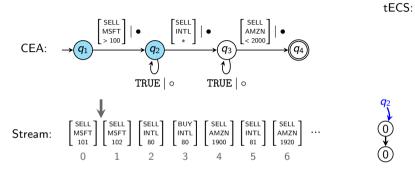


Algorithm crux:

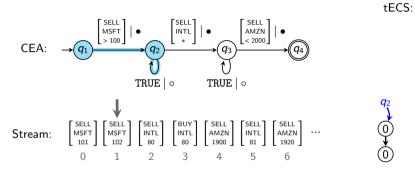
Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.



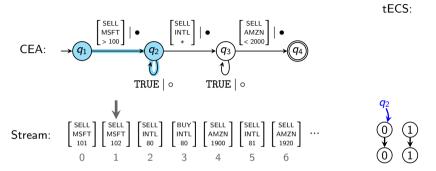
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.



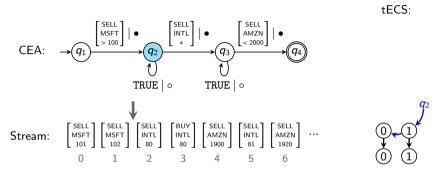
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.



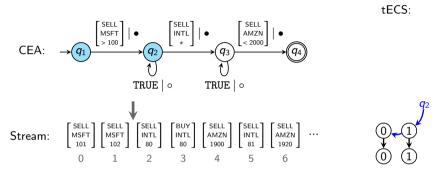
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.



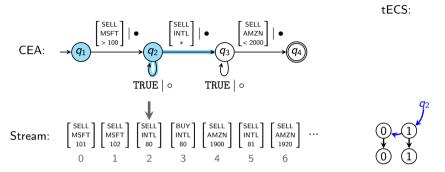
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.



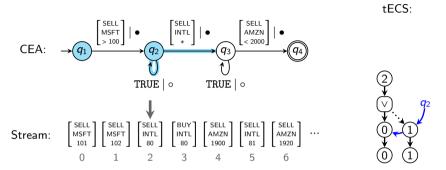
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.



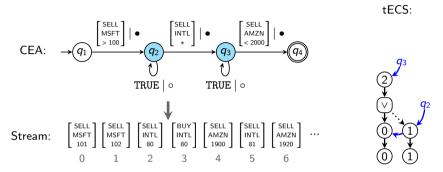
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.



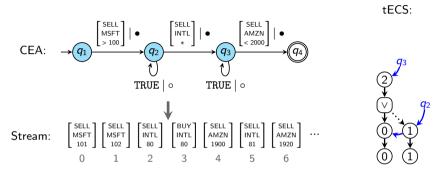
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.



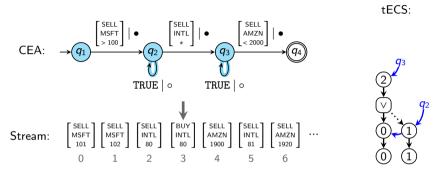
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.



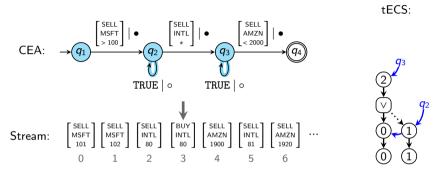
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.



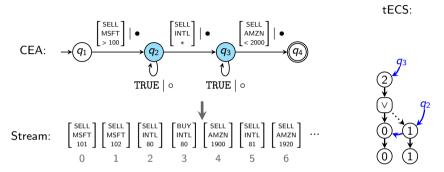
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.



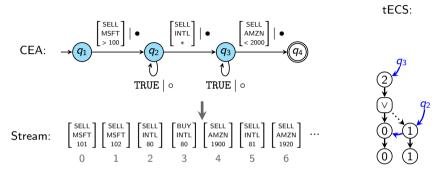
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.



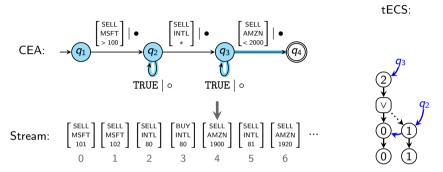
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.



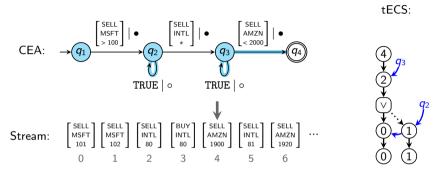
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.



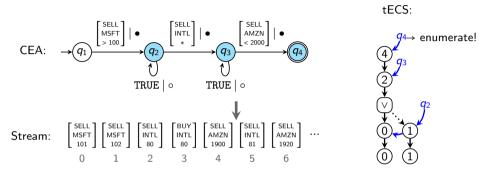
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.



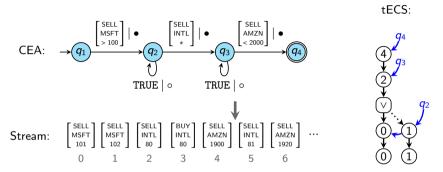
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.



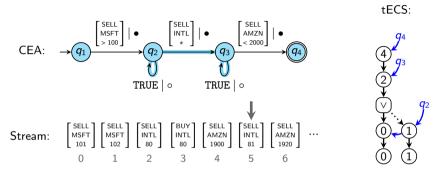
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.



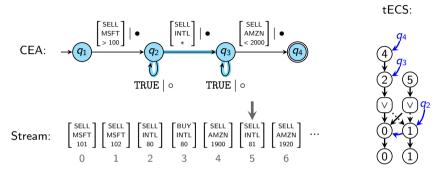
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.



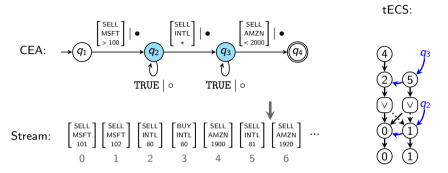
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.



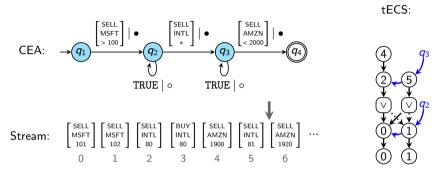
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.



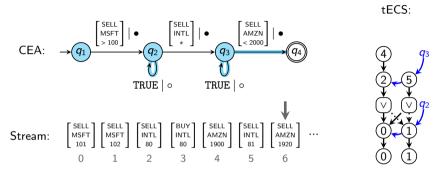
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.



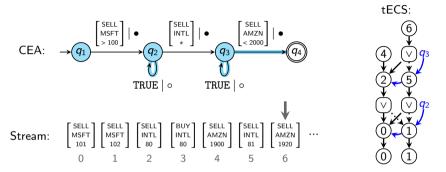
- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|CEA|)$, implying that we only take time $\mathcal{O}(|CEA|)$ per event. This is constant in data complexity.



- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.

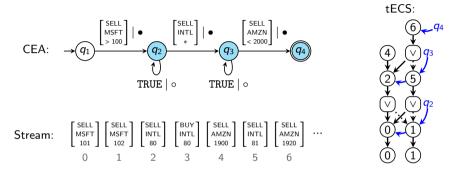


- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.



- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.

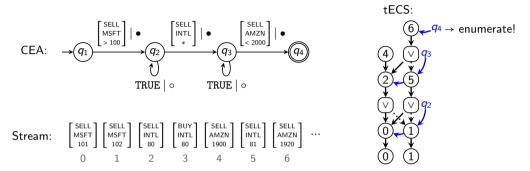
Evaluation Algorithm by Example



Algorithm crux:

- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of active CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|\mathsf{CEA}|)$, implying that we only take time $\mathcal{O}(|\mathsf{CEA}|)$ per event. This is constant in data complexity.

Evaluation Algorithm by Example



Algorithm crux:

- Incrementally build the (well-structured) tECS to represents all open complex events up to the current event.
- Maintain the set of *active* CEA states, and the open complex events they correspond to.
- Crucially, all bookkeeping is $\mathcal{O}(|CEA|)$, implying that we only take time $\mathcal{O}(|CEA|)$ per event. This is constant in data complexity.

Outline

A logic for CER

An automaton model for CER

Evaluation algorithm

The CORE complex event recognition engine

Open questions

CORE: COmplex event Recognition Engine

An open-source implementation [1] of our approach.

[1] https://github.com/CORE-cer/CORE

CORE: COmplex event Recognition Engine

An open-source implementation [1] of our approach.

1. Practical query language (CEQL) based on unary CEL.

2. Evaluation in constant update-time and output-linear delay, based on CEA.

3. CORE's performance is stable w.r.t query and time-window size.

4. CORE outperforms existing systems by up to 5 orders of magnitude.

[1] https://github.com/CORE-cer/CORE

| < list-of-variables > |
|-------------------------|
| < list-of-streams > |
| < CEL-formula > |
| < list-of-filters > |
| < list-of-attributes >] |
| < time-value >] |
| |

| SELECT | < list-of-variables > |
|---------------|-------------------------|
| FROM | < list-of-streams > |
| WHERE | < CEL-formula > |
| FILTER | < list-of-filters > |
| [PARTITION BY | < list-of-attributes >] |
| [WITHIN | < time-value >] |

Examples (Stock Market)

| SELECT | < list-of-variables > |
|---------------|-------------------------|
| FROM | < list-of-streams > |
| WHERE | < CEL-formula > |
| FILTER | < list-of-filters > |
| [PARTITION BY | < list-of-attributes >] |
| [WITHIN | < time-value >] |

Examples (Stock Market)

| | SELL] | SELL] | [SELL] | [BUY] | SELL] | [BUY] | BUY] | | (type) |
|---------|--------|--------|--------|-------|----------------------|-------|-------|--|---------|
| Stream: | MSFT | MSFT | INTL | INTL | SELL AMZN 1900 | INTL | AMZN | | (name) |
| | 101 | 102 | 80 | 80 | 1900 | 81 | 1920 | | (price) |

| SELECT | < list-of-variables > |
|---------------|-------------------------|
| FROM | < list-of-streams > |
| WHERE | < CEL-formula > |
| FILTER | < list-of-filters > |
| [PARTITION BY | < list-of-attributes >] |
| [WITHIN | < time-value >] |

Examples (Stock Market)

| | [SELL] | [SELL] | [SELL] | [BUY] | SELL] | [BUY] | [BUY] | (type) |
|---------|----------|----------|--------|-------|----------------------|-------|---------|------------|
| Stream: | MSFT | MSFT | INTL | INTL | SELL AMZN 1900 | INTL | AMZN | (name) |
| | 101 | 102 | 80 | 80 | 1900 | 81 | 1920 | (price) |

| SELECT | < list-of-variables > |
|---------------|-------------------------|
| FROM | < list-of-streams > |
| WHERE | < CEL-formula > |
| FILTER | < list-of-filters > |
| [PARTITION BY | < list-of-attributes >] |
| [WITHIN | < time-value >] |

Examples (Stock Market)

| | SELL] | SELL] | [SELL] | [BUY] | SELL] | [BUY] | [BUY] | (type) |
|---------|--------|--------|--------|-------|----------------------|-------|---------|------------|
| Stream: | MSFT | MSFT | INTL | INTL | SELL AMZN 1900 | INTL | AMZN | (name) |
| | 101 | 102 | 80 | 80 | 1900 | 81 | 1920 | (price) |

| < list-of-variables > |
|-------------------------|
| < list-of-streams > |
| < CEL-formula > |
| < list-of-filters > |
| < list-of-attributes >] |
| < time-value >] |
| |

| SELECT | < list-of-variables > |
|--------------|-------------------------|
| FROM | < list-of-streams > |
| WHERE | < CEL-formula > |
| FILTER | < list-of-filters > |
| PARTITION BY | < list-of-attributes >] |
| [WITHIN | < time-value >] |

Examples (Stock Market)

2. SELECT s, b FROM Stocks WHERE (BUY or SELL) as s; (BUY or SELL) as b PARTITION BY [name] WITHIN 5 minute

| SELECT | < list-of-variables > |
|--------------|-------------------------|
| FROM | < list-of-streams > |
| WHERE | < CEL-formula > |
| FILTER | < list-of-filters > |
| PARTITION BY | < list-of-attributes >] |
| [WITHIN | < time-value >] |

Examples (Stock Market)

| 2. | SELECT | s, b FROM Stocks |
|----|--------------|--|
| | WHERE | (BUY or SELL) as s; (BUY or SELL) as b |
| | PARTITION BY | [name] |
| | WITHIN | 5 minute |

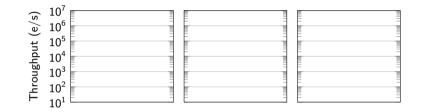
| Stream: | SELL | SELL | [SELL] | [BUY] | SELL AMZN 1900 10:25 | [BUY] | BUY | (type | be) |
|---------|-------|-------|--------|-------|-------------------------------|-------|-------|--------|-----|
| | MSFT | MSFT | INTL | INTL | AMZN | INTL | AMZN | (nam | ne) |
| | 101 | 102 | 80 | 80 | 1900 | 81 | 1920 | (price | ce) |
| | 10:00 | 10:02 | 10:10 | 10:14 | 10:25 | 10:30 | 10:33 | (time | ıe) |

| SELECT | < list-of-variables > | | |
|--------------|-------------------------|--|--|
| FROM | < list-of-streams > | | |
| WHERE | < CEL-formula > | | |
| FILTER | < list-of-filters > | | |
| PARTITION BY | < list-of-attributes >] | | |
| [WITHIN | < time-value >] | | |

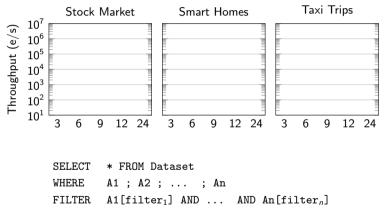
Examples (Stock Market)

| 2. | SELECT s, b FROM Stocks | | | | | |
|----|-------------------------|--|--|--|--|--|
| | WHERE | (BUY or SELL) as s; (BUY or SELL) as b | | | | |
| | PARTITION BY | [name] | | | | |
| | WITHIN | 5 minute | | | | |

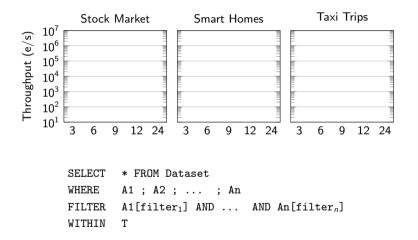
| | SELL | SELL | SELL | [BUY] | SELL | [BUY] | BUY | (type) |
|---------|-------|-------|-------|-------|--------------|-------|-------|---------|
| Stream: | MSFT | MSFT | INTL | INTL | AMZN | INTL | AMZN | (name) |
| | 101 | 102 | 80 | 80 | AMZN 1900 | 81 | 1920 | (price) |
| | 10:00 | 10:02 | 10:10 | 10:14 | 10:25 | 10:30 | 10:33 | (time) |







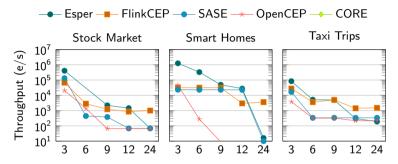
WITHIN T



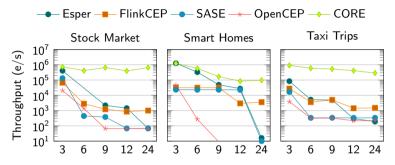
We use sequences of length n = 3, 6, 9, 12, 24.



- 1. Esper (*industry*)
- 2. FlinkCEP (*industry*)
- 3. SASE (academy)
- 4. OpenCEP (academy)
- 5. CORE



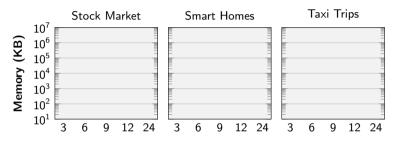
--- Esper --- FlinkCEP --- SASE --- OpenCEP --- CORE Taxi Trips Stock Market Smart Homes 10^{7} Throughput (e/s) 10^{6} 10⁵ 10^{4} 10³ 10² 10^1 3 6 12 24 3 6 9 12 24 3 6 9 12 24 9



CORE is up to 4 orders of magnitude faster than other systems

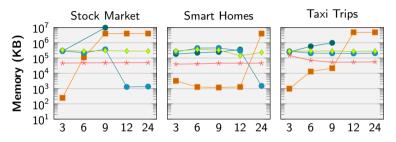
Experiments: Sequence queries (memory)

--- Esper --- FlinkCEP --- SASE --- OpenCEP --- CORE



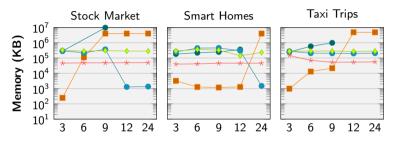
Experiments: Sequence queries (memory)

--- Esper --- FlinkCEP --- SASE --- OpenCEP --- CORE



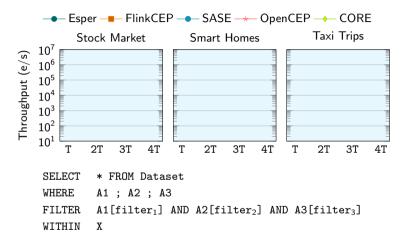
Experiments: Sequence queries (memory)

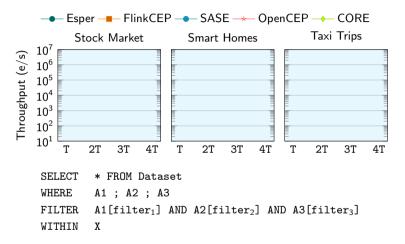
--- Esper --- FlinkCEP --- SASE --- OpenCEP --- CORE



CORE is stable in the memory usage







We use time-windows size X = T, 2T, 3T, 4T.





Conclusions

1. CORE is orders of magnitude faster than other systems.



Conclusions

- 1. CORE is orders of magnitude faster than other systems.
- 2. CORE is not affected by the query or time-windows size.



In the paper [1], we show similar results with other query workloads

[1] M. Bucchi, A. Grez, A. Quintana, C. Riveros, and S. Vansummeren "CORE: a Complex Event Recognition Engine", VLDB 2022.

Outline

A logic for CER

An automaton model for CER

Evaluation algorithm

The CORE complex event recognition engine

Open questions

Time Model

Time Model

Limitation: No out-of-order events

- Time is implicit, given by arrival order
- Crucial property for CEA evaluation: Events arrive in timestamp order

Time Model

Limitation: No out-of-order events

- Time is implicit, given by arrival order
- Crucial property for CEA evaluation: Events arrive in timestamp order

Open question: What is the impact of out-of-order events on

- Language design and expressiveness ?
- Evaluation model (CEA) and complexity ?

Limitation: CORE and CEQL are based on unary CEL

Limitation: CORE and CEQL are based on unary CEL

Unary CEL does not allow event correlation.

Example: unsupported $\varphi = (B; S)$ FILTER $B[id] = S[id] \land B[volume] > S[volume]$

Limitation: CORE and CEQL are based on unary CEL

- Unary CEL does not allow event correlation.
- ... partially solved by PARTITION BY in CEQL for equality in limited cases.

Example: unsupported

 $\varphi = (B; S)$ FILTER $B[id] = S[id] \land B[volume] > S[volume]$

Limitation: CORE and CEQL are based on unary CEL

- Unary CEL does not allow event correlation.
- ... partially solved by PARTITION BY in CEQL for equality in limited cases.

Example: unsupported

 $\varphi = (B; S)$ FILTER $B[id] = S[id] \land B[volume] > S[volume]$

Open questions:

- What is the impact of moving to k-ary predicates, k > 1 on Language expressiveness ?
- What is the right computational model (à la CEA) with binary predicates ?
- How does this affect complexity?

Processing versus recognition

Limitation: CORE, CEQL, and CEL focus on complex event recognition

Processing versus recognition

Limitation: CORE, CEQL, and CEL focus on complex event recognition Other features in the literature that focus on *processing* of complex events are not supported:

- aggregation
- integration of non-event data sources
- parallel or distributed execution

Processing versus recognition

Limitation: CORE, CEQL, and CEL focus on complex event **recognition** Other features in the literature that focus on *processing* of complex events are not supported:

- aggregation
- integration of non-event data sources
- parallel or distributed execution

Open questions:

- What is the right language for CER + aggregation?
- What is the right computational model (à la CEA) in the presence of aggregation?
- How does aggregation affect evaluation complexity?

Getting to the CORE of Complex Event Recognition

Stijn Vansummeren UHasselt, Data Science Institute